YASKAWA

GP12

Efficient, High-Speed Robot



Highest payload, speeds and wrist allowable moment in its class

Space-efficient design

Engineered for easy installation, operation and maintenance

Specifications

12 kg payload 1,440 mm horizontal reach 2,511 mm vertical reach ±0.08 mm repeatability

Applications

Assembly

Material Handling

Packaging

Controllers

YRC1000

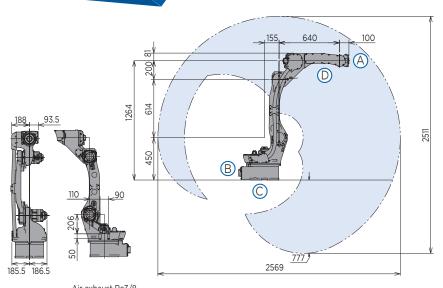
MLX300 * Software Option

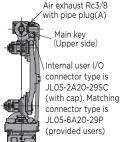


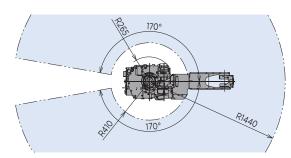
- Increase your productivity with the fast and efficient GP12 robot.
- All axis speeds have been increased by up to 15% surpassing other robots in its class.
- Reduced interference design allows close proximity placement of robots.
- Maximum reduction of acceleration/ deceleration times for all robot positions.
- Hollow arm structure eliminates cable interference.
- Highest wrist allowable moment for accurate and repeatable handling.
- Higher payload allows wider range of tooling integration such as double gripper for multi-handling operations.
- IP67-rated wrist and IP54 body (IP65 optional).
- Single power and control cable reduces wiring time and increases work efficiency.

- New robot harness design for improved diagnostics and maintenance.
- Home position data can be saved without battery connection for easy maintenance.
- Ideal for high-volume assembly, handling and packaging applications.
- The GP-series robots are controlled by Yaskawa's new high-performance YRC1000 controller that is built to a global standard and does not require a transformer for input voltages ranging from 380VAC to 480VAC. It is highly compact, resulting in reduced space requirements. Its I/O communication speed is improved by as much as 50% for improved work efficiency.

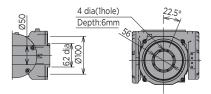
GP12 Robot







VIEW A



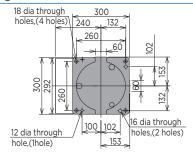
VIEW B



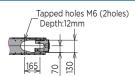
Internal User Air Line Rc3/8 with pipe plug(A)

/ Internal user wiring connector type is JL05-2A20-29PC (with cap) Matching connector type is JL05-6A20-29S (provided users)

VIEW C



VIEW D



All dimensions are metric (mm) and for reference only.

Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS				
Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [N•m]	Allowable moment of inertia [kg•m²]
S	±170	260	-	-
L	+155/-90	230	-	-
U	+150/-85	260	-	-
R	±200	470	22	0.65
В	±150	470	22	0.65
Т	±455	700	9.8	0.17

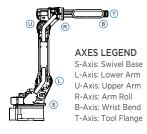
Mounting Options: Floor, Wall or Ceiling

^{*} The MLX300 software option is not available for use with arc or spot welding, coating, dispensing, cutting or other "path control" applications. MLX300 fieldbus cards, I/O cards and vision equipment must be purchased separately from the supplier. All peripherals are programmed using a PLC.

GP12	
6	
12	
±0.08	
1,440	
2,511	
130	
17 conductors (+ ground)	
(1) 3/8" connection	
380-480 VAC	
1.5	

Options

- · Robot risers and base plates
- MotoSight™ 2D and 3D vision systems



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