

1990 - 1994

Design Of The Spatial 4c Mechanism For Rigid Body Guidance

```
@inproceedings{1995082503533 ,
  title = {Design of the spatial 4C mechanism for rigid body guidance},
  journal = {American Society of Mechanical Engineers, Design Engineering
  Division (Publication) DE},
  author = {Larochelle, Pierre and McCarthy, J.Michael},
  volume = {70},
  number = {pt 1},
  year = {1994},
  pages = {135 - 142},
  address = {Minneapolis, MN, USA}
}
```

Designing Planar Mechanisms Using A Bi-invariant Metric In The Image Space Of So(3)

```
@inproceedings{1995082503544 ,
  title = {Designing planar mechanisms using a bi-invariant metric in the
  image space of SO (3)},
  journal = {American Society of Mechanical Engineers, Design Engineering
  Division (Publication) DE},
  author = {Larochelle, Pierre and McCarthy, J.Michael},
  volume = {70},
  number = {pt 1},
  year = {1994},
  pages = {221 - 228},
  address = {Minneapolis, MN, USA}
}
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Performance Evaluation Of Cooperating Robot Movements Using Maximum Load Under time optimal Control

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@inproceedings{1991120365477 ,
  title = {Performance evaluation of cooperating robot movements using
  maximum load under time-optimal control},
  journal = {Proceedings - IEEE International Conference on Robotics and
  Automation},
  author = {Larochelle, Pierre and McCarthy, J.M.},
  volume = {3},
  year = {1991},
  pages = {2612 - 2617},
  issn = {10504729},
  address = {Sacramento, CA, USA},
  URL = {http://dx.doi.org/10.1109/ROBOT.1991.132022}
}
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Static Analysis Of Spherical Nr Kinematic Chains With Joint Friction

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@inproceedings{1993040682513 ,
title = {Static analysis of spherical nR kinematic chains with joint
friction},
journal = {American Society of Mechanical Engineers, Design Engineering
Division (Publication) DE},
author = {Larochelle, Pierre and McCarthy, J.M.},
volume = {47},
year = {1992},
pages = {173 - 177},
address = {Scottsdale, AZ, USA}
}
```