

1995 - 1999

Algebraic Motion Approximation With Nurbs Motions And Its Application To Spherical

MechanismSynthesis

```
@article{ge:529,  
  author = {Q. Jeffrey Ge and P. M. Larochelle},  
  title = {Algebraic Motion Approximation With NURBS Motions and Its  
  Application to Spherical Mechanism Synthesis},  
  publisher = {ASME},  
  year = {1999},  
  journal = {Journal of Mechanical Design},  
  volume = {121},  
  number = {4},  
  pages = {529-532},  
  url = {http://link.aip.org/link/?JMD/121/529/1},  
  doi = {10.1115/1.2829493}  
}
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Design of Cooperating Spherical Rpr Robots

```
@inproceedings{1997453824872 ,  
  language = {English},  
  title = {Design of cooperating spherical RPR robots},  
  journal = {Proceedings - IEEE International Conference on Robotics and  
  Automation},  
  author = {Larochelle, Pierre M.},  
  volume = {3},  
  year = {1997},  
  pages = {2115 - 2120},  
  issn = {10504729},  
  address = {Albuquerque, NM, USA}  
}
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Integrating Spatial Motion Generation Into The Engineering Curriculum

```
@inproceedings{1996483356102 ,  
  title = {Integrating spatial motion generation into the engineering  
  curriculum},  
  journal = {ASEE Annual Conference Proceedings},  
  author = {Larochelle, Pierre},  
  volume = {2},  
  year = {1995},  
  pages = {1913 - 1918},  
  issn = {01901052},  
  address = {Anaheim, CA, USA}  
}
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On The Design of Spatial 4c Mechanisms For Rigid Body Guidance Through Four

Positions

```
@inproceedings{1997183566383 ,
title = {On the design of spatial 4C mechanisms for rigid-body guidance
through 4 positions},
journal = {American Society of Mechanical Engineers, Design Engineering
Division (Publication) DE},
author = {Larochelle, Pierre M.},
volume = {82},
number = {1},
year = {1995},
pages = {825 - 832},
address = {Boston, MA, USA}
}
```

Planar Motion Synthesis Using An Approximate Bi-invariant Metric

```
@article{larochelle:646,
author = {P. Larochelle and J. M. McCarthy},
title = {Planar Motion Synthesis Using an Approximate Bi-Invariant
Metric},
publisher = {ASME},
year = {1995},
journal = {Journal of Mechanical Design},
volume = {117},
number = {4},
pages = {646-651},
url = {http://link.aip.org/link/?JMD/117/646/1},
doi = {10.1115/1.2826735}
}
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Spherical Mechanism Synthesis In Virtual Reality conf

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@article{furlong:515,
author = {T. J. Furlong and J. M. Vance and P. M. Larochelle},
title = {Spherical Mechanism Synthesis in Virtual Reality},
publisher = {ASME},
year = {1999},
journal = {Journal of Mechanical Design},
volume = {121},
number = {4},
pages = {515-520},
url = {http://link.aip.org/link/?JMD/121/515/1},
doi = {10.1115/1.2829491}
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