

2005 - 2009

A displacement metric for finite sets of rigid body displacements

```
@article{venkataramanujam:1463,  
author = {Venkatesh Venkataramanujam and Pierre Larochelle},  
title = {A Displacement Metric for Finite Sets of Rigid Body  
Displacements},  
publisher = {ASME},  
year = {2008},  
journal = {ASME Conference Proceedings},  
volume = {2008},  
number = {43260},  
pages = {1463-1469},  
url = {http://link.aip.org/link/abstract/ASMECP/v2008/i43260/p1463/s1},  
doi = {10.1115/DETC2008-49554}  
}
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A Distance Metric For Finite Sets Of Rigid-body Displacements Via The Polar Decomposition

```
@article{larochelle:883,  
author = {Pierre M. Larochelle and Andrew P. Murray and Jorge Angeles},  
title = {A Distance Metric for Finite Sets of Rigid-Body Displacements  
via the Polar Decomposition},  
publisher = {ASME},  
year = {2007},  
journal = {Journal of Mechanical Design},  
volume = {129},  
number = {8},  
pages = {883-886},  
keywords = {singular value decomposition; design engineering;  
geometry},  
url = {http://link.aip.org/link/?JMD/129/883/1},  
doi = {10.1115/1.2735640}  
}
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Approximate Motion Synthesis Of Spherical Kinematic Chains

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@article{venkataramanujam:389,  
author = {Venkatesh Venkataramanujam and Pierre Larochelle},  
title = {Approximate Motion Synthesis of Spherical Kinematic Chains},  
publisher = {ASME},  
year = {2007},  
journal = {ASME Conference Proceedings},  
volume = {2007},  
number = {48094},  
pages = {389-397},  
url = {http://link.aip.org/link/abstract/ASMECP/v2007/i48094/p389/s1},  
doi = {10.1115/DETC2007-34372}  
}
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Collision Detection Of Cylindrical Rigid Bodies For Motion Planning

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@inproceedings{20065210327602 ,
  language = {English},
  copyright = {Compilation and indexing terms, Copyright 2010 Elsevier
  Inc.},
  copyright = {Compendex},
  title = {Collision detection of cylindrical rigid bodies for motion
  planning},
  journal = {Proceedings - IEEE International Conference on Robotics and
  Automation},
  author = {Ketchel, John and Larochelle, Pierre},
  volume = {2006},
  year = {2006},
  pages = {1530 - 1535},
  issn = {10504729},
  address = {Orlando, FL, United states},
  URL = {http://dx.doi.org/10.1109/ROBOT.2006.1641925}
}
```

Collision Detection Of Cylindrical Rigid Bodies Using Line Geometry

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@article{ketchel:811,
  author = {John S. Ketchel and Pierre M. Larochelle},
  title = {Collision Detection of Cylindrical Rigid Bodies Using Line
  Geometry},
  publisher = {ASME},
  year = {2005},
  journal = {ASME Conference Proceedings},
  volume = {2005},
  number = {47446},
  pages = {811-825},
  url = {http://link.aip.org/link/abstract/ASMECP/v2005/i47446/p811/s1},
  doi = {10.1115/DETC2005-84699}
}
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Sphinxcam-proe Computer-aided Modeling & Manufacturing Of Spherical Mechanisms Via The Web

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@inproceedings{20064810273126 ,
  language = {English},
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  Inc.},
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  title = {SphinxCAM-Pro|E: Computer-aided modeling  manufacturing of
  spherical mechanisms via the web},
  journal = {Proceedings of the ASME Design Engineering Technical
  Conference},
  author = {Larochelle, Pierre M. and Schuler, Jason M. and Ketchel, John
  S.},
  volume = {2006},
  year = {2006},
  address = {Philadelphia, PA, United states}
}
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Computer-aided Manufacturing Of Spherical Mechanisms

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@article{20065010303887 ,
  language = {English},
  copyright = {Compilation and indexing terms, Copyright 2010 Elsevier
  Inc.},
  copyright = {Compendex},
  title = {Computer-aided manufacturing of spherical mechanisms},
  journal = {Mechanism and Machine Theory},
  author = {Ketchel, John S. and Larochelle, Pierre M.},
  volume = {42},
  number = {2},
  year = {2007},
  pages = {131 - 146},
  issn = {0094114X},
  URL = {http://dx.doi.org/10.1016/j.mechmachtheory.2006.09.007}
}
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Computer-aided Modeling And Manufacturing Of Spherical Mechanisms Via A Novel Web Tool

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@article{schuler:339,
  author = {J. Schuler and J. Ketchel and P. Larochelle},
  title = {Computer-Aided Modeling and Manufacturing of Spherical
  Mechanisms via a Novel Web Tool},
  publisher = {ASME},
  year = {2007},
  journal = {Journal of Computing and Information Science in
  Engineering},
  volume = {7},
  number = {4},
  pages = {339-346},
  url = {http://link.aip.org/link/?CIS/7/339/1},
  doi = {10.1115/1.2795307}
}
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Effect Of Tracking Flat Reflector Using Novel Auxiliary Drive Mechanism On The Performance Of Stationary Photovoltaic Module

```
@article{kulkarni:351,  
author = {Sudhir Kulkarni and Saurabh Tonapi and Pierre Larochelle and  
Kunal Mitra},  
title = {Effect of Tracking Flat Reflector Using Novel Auxiliary Drive  
Mechanism on the Performance of Stationary Photovoltaic Module},  
publisher = {ASME},  
year = {2007},  
journal = {ASME Conference Proceedings},  
volume = {2007},  
number = {43009},  
pages = {351-356},  
url = {http://link.aip.org/link/abstract/ASMECP/v2007/i43009/p351/s1},  
doi = {10.1115/IMECE2007-42973}  
}
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Interactive Visualization Of The Coupler Surfaces Of The Spatial 4c Mechanism

```
@article{larochelle:1122,  
author = {Pierre M. Larochelle and Agnes M. Agius},  
title = {Interactive Visualization of the Coupler Surfaces of the  
Spatial 4C Mechanism},  
publisher = {ASME},  
year = {2005},  
journal = {Journal of Mechanical Design},  
volume = {127},  
number = {6},  
pages = {1122-1128},  
keywords = {bars; couplings; graphical user interfaces; mechanical  
engineering computing},  
url = {http://link.aip.org/link/?JMD/127/1122/1},  
doi = {10.1115/1.2049067}  
}
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Projection Metrics For Rigid-body Displacements

```
@article{larochelle:1025,  
author = {Pierre M. Larochelle and Andrew P. Murray},  
title = {Projection Metrics for Rigid-Body Displacements},  
publisher = {ASME},  
year = {2005},  
journal = {ASME Conference Proceedings},  
volume = {2005},  
number = {47446},  
pages = {1025-1030},  
url = {http://link.aip.org/link/abstract/ASMECP/v2005/i47446/p1025/s1},  
doi = {10.1115/DETC2005-84698}  
}
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Self-collision Detection In Spatial Closed Chains

```
@article{ketchel:092305,  
author = {John S. Ketchel and Pierre M. Larochele},  
title = {Self-Collision Detection in Spatial Closed Chains},  
publisher = {ASME},  
year = {2008},  
journal = {Journal of Mechanical Design},  
volume = {130},  
number = {9},  
eid = {092305},  
numpages = {9},  
pages = {092305},  
url = {http://link.aip.org/link/?JMD/130/092305/1},  
doi = {10.1115/1.2965363}  
}
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Systematic Process For Constructing Spherical Four Bar Mechanisms

```
@inproceedings{2006129777174 ,  
copyright = {Compilation and indexing terms, Copyright 2010 Elsevier  
Inc.},  
title = {Systematic process for constructing spherical four-bar  
mechanisms},  
journal = {American Society of Mechanical Engineers, Design Engineering  
Division (Publication) DE},  
author = {Turner, Michael L. and Murray, Andrew P. and Perkins, David  
A. and Larochele, Pierre M.},  
volume = {118 A},  
number = {1},  
year = {2005},  
pages = {299 - 305},  
address = {Orlando, FL, United states}  
}
```

Unifying Assessment Of Freshman Design Teams With Team Project Management

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@inproceedings{2005319271517 ,  
language = {English},  
copyright = {Compilation and indexing terms, Copyright 2010 Elsevier  
Inc.},  
title = {Unifying assessment of freshman design teams with team project  
management},  
journal = {ASEE Annual Conference and Exposition, Conference  
Proceedings},  
author = {Larochele, Pierre},  
year = {2005},  
pages = {14791 - 14800},  
address = {Portland, OR, United states}  
}
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